ROTATIONAL EFFECTS ON VORTEX SHEDDING BEHAVIOUR OF A CYLINDER WITH SURFACE ROUGHNESS – AN EXPERIMENTAL PIV AND COMPUTATIONAL APPROACH

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Abstract- Mostly a wake flow can contribute to unwanted vortex shedding and vibration of different frequencies. If this phenomenon continues for a long time, a bluff body is likely to experience damage caused by inconsistent flow, which can lead to failure. This paper examines vortex shedding behaviour behind a rotating cylinder with surface roughness. Experimental and numerical two-dimensional approaches are taken. In a wind tunnel experiment, there is free-stream velocities of uniform incompressible flow around the circular cylinder (D=50mm). Surface roughness at 5.0µm<Ra<80µm is applied to the cylinder surface. The Reynolds number is in the range 2000<Re<42000, based on the cylinder diameter, and the rotation rates are 0<α<7.9 (ratio of the surface speed) and the free-stream speed is varied in the range 0.65–13.21m/s. A comparison is made with a stationary cylinder and three degrees of surface roughness on rotating circular cylinders. Sand paper is used to establish the rough profile. Particle Image Velocimetry (PIV) measures flow behind a rotating cylinder and captures images of vortices shedding during the experiment. Computational Fluid Dynamics (CFD) simulation is carried out to verify and analyse the vortex shedding formation. This can indicate the most suitable placement of the experimental device so the roughness suppresses vortex shedding. The PIV and CFD results are compared and confirm that the velocity behind a rotating cylinder at low and high speeds is affected by surface roughness. It is concluded that vortex shedding in the flow behaviour behind a rotating cylinder is generated in the far-wake of a cylinder with surface roughness.

Keywords- Circular cylinder, Surface roughness, Reynolds number, Lift and drag coefficient, Velocity profile.

I. INTRODUCTION

The effect on fluid dynamics when a circular cylinder is placed in flow has been studied, to understand the practical implications. Typical industrial applications which involve rotating cylinders include risers associated with marine engineering, offshore structures, buildings and bridges, pipelines, and heat exchanger tubes. Substantial areas in the flow can contain unsteady forces that develop from vortex shedding in the wake. These movements can potentially cause damage to the structure of bluff bodies. Research into these phenomena has attempted to identify methods to reduce the detrimental forces that develop when flow passes around objects. Sumer observes that at low Reynolds number (Re) there is symmetric flow past a circular cylinder.

However, increasing Reynolds number results in separation behind the cylinder, this interrupts the flow and vortex shedding can develop. At 40<Re<200, laminar vortex shedding takes place in the wake and at Re=200–300 there is a transition to turbulence. The peak of turbulent flow leads to laminar boundary layer separation at the subcritical region 300<Re<3x10^5. Payne carried out some initial investigation into flow disturbance at Re=40–100. Both experimental and numerical analysis has been used to investigate flow at different Reynolds number, which is reported in the literature. The simulations that are carried out using Computational Fluid Dynamics (CFD) techniques are predominantly two-dimensional.

Research into flow patterns that occur behind a rotating circular cylinder is sparse, but contributions have been made through experiments carried out by Badr et al., and Kimura et al.. The experiments have concentrated on speeds of α<2.5 and visual inspection of flow behaviour and vortex shedding. The observations are at rotational speeds below a critical value, which is approximately α<2.0 at Re>1000. It was found that flow in the wake became asymmetric and there was deflection of the cylinder to one side at α>0. Until now the literature has not considered quantitative measurement of velocity fields and vorticity in the wake of a rotating cylinder, but concentrated on the vortex dynamics.

Studies on flow have examined rotating oscillating circular cylinders. The oscillation has either been in-line, lateral, or rotational. Lock-in is observed when the lateral oscillation frequency synchronises with the natural vortex shedding frequency. During lock-in, regularity and two-dimensionality predominate in vortex shedding and the patterns of vortices. In contrast, lock-in associated with in-line oscillation of rotating cylinders is initiated when the frequency of the fluctuating drag force is approached, due to natural vortex shedding. Moreover, when the cylinder oscillation and natural vortex shedding frequencies begin to coincide, synchronisation is introduced between the vortex shedding and cylinder movement in rotationally oscillating cylinders. These attributes facilitate studies of the shedding mechanism and vortex street dynamics and development. Suppression of vortex shedding is possible by controlling the
interface between cylinder oscillation and natural vortex shedding frequencies, particularly at very high speeds.

The association between flow and cylinder movement can begin to form when a circular cylinder is rotating at a steady speed. An example is potential flow, in which the rotation results in acceleration of flow on one side and deceleration on the other. Flow is normally a consequence of the Reynolds number and the non-dimensional rotation speed. This is expressed as the ratio of circumferential speed at the cylinder surface to free-stream velocity of the uniform cross-flow ($\alpha=\omega D/2U_0$) where, D is the diameter, $\omega$ is the angular rotation speed of the cylinder, and $U_0$ is the free-stream velocity.

To predict flow, there is a range of aspects that require clarification and both experimental and computational approaches are beneficial. In this research the focus is on observation and quantification of two-dimensional (2D) flow behind a counter-clockwise rotating cylinder. The cylinder is modified by different degrees of surface roughness. Jose Luiz Duarte Ribeiro studies drag forces and pressure associated with roughness in the range 50000$\leq$Re$\leq$400000 and unevenness heights 0.0018$\leq$k/$d$$\leq$0.0123. His experiments involve surface modification using sand paper, wire mesh screen, and ribs, in which the application of ribs produces the smallest relative difference. Shih et al. demonstrates the flow on smooth and rough cylinders in steady and unsteady flows over a maximum achievable range of Reynolds number. However, both experimental approaches involve a stationary circular cylinder and results are validated against similar studies reported in the literature.

The aim of our research is to analyse data originating from experimental and numerical investigation of vortex shedding behaviour. The research is concerned with four grades of surface roughness and an atomiser is used for seeding in the towing tank of a wind tunnel. The effect of Reynolds number in the range 2000$<Re<42000$ and varied rotation rates are measured. The focus is on identifying changes in vortex shedding behaviour associated with different rate ratios in respect of rotation and roughness. In addition, the results are reviewed by a comparison of Particle Image Velocimetry (PIV) and CFD findings.

II. METHODOLOGY EXPERIMENTAL SET-UP

Analysing the scaling used in the construction of the cylinder is an important consideration, to ensure the experimental results are reliable and suitable for analysis. Cylinders with degrees of surface roughness are prepared (Table 1). Lightweight materials are used to fabricate the cylinders. The body is made of hollow ($D = 50$ mm) aluminium tubing and the cylinder length is 300 mm. The roughness is created by interspersing the surface of a smooth cylinder with non-uniform pieces of sandpaper. Profile analysis of the resulting surface roughness is carried out (Alicona IF-Profiler).

Table 1: Average roughness profiles of the circular cylinders

<table>
<thead>
<tr>
<th>Type</th>
<th>Roughness</th>
</tr>
</thead>
<tbody>
<tr>
<td>Cylinder A - (Smooth)</td>
<td>5.078</td>
</tr>
<tr>
<td>Cylinder B - (Silicon Carbide #80)</td>
<td>39.88</td>
</tr>
<tr>
<td>Cylinder C - (Silicon Carbide #60)</td>
<td>60.15</td>
</tr>
<tr>
<td>Cylinder D - (Silicon Carbide #36)</td>
<td>76.39</td>
</tr>
</tbody>
</table>

An open-circuit wind tunnel is used to measure the forces produced by rotating cylinders with different surface roughness. The rotation is controlled by a lightweight motor attached to the cylinder which is placed in a 300 mm x 300 mm test section of a wind tunnel. The maximum velocity is 36 m/s, moderated by an electronic control. A force measurement system, data acquisition unit, and a computer, form the measurement set-up (Fig. 1).

![Fig. 1: Schematic of the experimental set-up](image)

West and Apelt report a slight pressure distribution around a circular cylinder dependent on the blockage ratio. Where the blockage represents less than 6% of the wind tunnel, the effects are negligible. In a study by Park et al., there is a 4.2% blockage ratio for a 2D cylinder and their conclusions confirm the negligible blockage effect. Based on these finding, the blockage effect is disregarded for the purposes of the current study.

An AC motor with a maximum rotation of 10000 rpm generates the motion. Slight modification to the casing and shaft is carried out, the total weight of the lightweight smart motor (LWSM) is under 1 kg, and the assembly method is simple. The motor is mounted horizontally inside the wind tunnel without any support. The rotation of the motor causes minimal vibrational effects on measurements of the aerodynamic forces. The overall simplicity, rigidity, and precision of joints between the motor and cylinder, result in an efficient and robust experimental set-up (Fig. 2). A two-step calibration
of the motor takes place, the first carried out before mounting in the wind tunnel. A magnetic gauge is used to contain displacement due to vibration at points on the cylinder to around ±0.15mm. The subsequent calibration in the wind tunnel first takes readings without free-stream velocity then with incoming free-stream velocity as is repeated before each test.

PIV is used to measure flow behind the counterclockwise rotating circular cylinder. It captures images of the vortex shedding during each experiment. The PIV consists of a CCD camera (Digital monochrome progressive scan camera: Flow Sense M2 10bits) with a 1600 x 1186 pixels spatial resolution image. A continuous-wave Nd:YAG laser captures images which are then stored in the computer. The flow area is illuminated by long exposure to a laser-generated light sheet and a mirror reflects it 90°. A convex and cylindrical lens produces a narrow sheet of light. In the test section the laser sheet is 1.0 mm and the thickness is controlled. Seeding using cornoil in the atomiser is used during visual inspection. The oils released at high pressure into the test section of the wind tunnel by a central air unit. The average corn oil particle diameter range is 1–2µm.

Images are captured at intervals of 100 ms to record the evolution of flow structure behind the rotating cylinder. The regularity corresponds to about 1% in the characteristic formation period of a large-scale vortex. Using the cross-correlation 2-frame method, 800 simultaneous velocity fields are obtained.

A comparison is made of the wake behind a cylinder with Reynolds number 2000 ≤ Re ≤ 42500. The field of view is 120 x 120 mm² (Fig. 3).

III. NUMERICAL SET-UP

ANSYS FLUENT® commercial CFD software simulates the flows involving rotation and surface roughness. The geometry of the cylinder is modeled with the Re value to simulate the surface roughness. The surface roughness is interpreted as a collection of minute step function profiles along the surface, based on approximation of the actual cylinder surface profile (Fig. 4). There are, nevertheless, limitations inherent in this method, as finer irregularities cannot be detected. To improve the method, it is possible to approximate the actual rough surface onto the geometry using the average heights of the irregular surface. The irregular roughness is measured in micron per meter (μm).

Simulations at various Reynolds number based on the same cylinder configuration in the experimental setup are used to predict the forces around the rotating cylinder (2000≤Re≤42000). With the cylinder centre at x=y=0, the simulation confirms –0.7≤x/D≤1.7 and –0.3≤y/D≤0.3, where x and y denote respectively the stream wise and transverse directions. At the velocity inlet on the left, uniform inflow (Ui) enters and then exists via the pressure outlet at the right (Fig. 5). The rotational velocity is prescribed and there is no-slip conditions at the cylinder wall, similar to testing carried out by Stojkovic et al., Karabelas et al., Srinivas et al., Fujisawa et al., Rajani et al., and Mahbubar et al. In the computational study, steady incompressible RANS equations are solved using implicit and segregated methods. The convective terms and viscous terms are discretised by second order upwind and central discretisation techniques respectively. The SIMPLE algorithm is used for coupling of the pressure and velocity.

Several blocks comprise the flow domain with multiple mesh densities to facilitate capture of local flow resolution at large velocity gradients. Micron-sized spacing and sizing is used in the design of the mesh points and surface roughness profile respectively, interspersed along the cylinder designed
in ABAQUS software then converted to gambit files. Commercial mesh generation package GAMBIT is used in the mesh generation. The simulation is based on a typical structured mesh (Fig. 5). The $y^+$ value near the cylinder surface is close to 1 to capture the effect of surface roughness.

The turbulent flow is modelled using Spalart-Allmaras (S-A) as it is cost-effective and highly accurate in simulations involving boundary layers exposed to adverse pressure gradients, as discussed by Willis et al., Krishnan et al., Martin et al., Takahashi et al..

IV. RESULTS AND DISCUSSION FLOW PATTERN

The experiment and simulation results (Fig. 6) show unsteady flow for Re = 2083 at zero-rotating (Cylinder A) in the near-wake directly behind the cylinder. Using phases for the same Reynolds number, the velocity vector directions and corresponding vorticity contours are visible, confirming the alternating formation, convection, and diffusion of vortices. Both images show velocity vectors are present in a high velocity near-wake region. A saddle point (solid circle) indicates the unsteady boundary layer separation at the surface of the cylinder (V1). The PIV shows an enlarged vortex core with an almost similar pattern to the numerical representation. The magnitudes of velocity also have similar values, especially adjacent to the cylinder. The disparity is in the delay in vortex formation behind the cylinder at location V1. The cause is the turbulence model used in the simulation.

After making a comparison of the methods, the S-A model is deemed incompatible with the flow type generated by a rough cylinder. The incidences of vortex shedding show small flow reversals within the shedding circle, particularly evident in the simulation. Over a long time period the phenomena would result in damage and potentially failure of bluff bodies.

The velocity vectors all have low magnitude values adjacent to the cylinder because the free-stream velocity is only 0.65 m/s. A small saddle point is triggered in the near-wake area behind the cylinder (V2). There is severe distortion as the vortices are still forming in relation to the vortex point. This indicates a reversal of flow vector direction is taking place after the saddle point. A vortex core with a small configuration is generated, but will not affect a large bluff body. The movement of shed vortices in the far-wake region, is at a nearly constant convective velocity. The near-wake flow structure is similar in both the experimental and simulation approaches and concurs with findings observed by Kuo et al. [9].

V. VELOCITY PROFILE

Figure 7 describes the dimensionless velocity profile at the symmetry line ($y=0$) in the range $10000<\text{Re}<20000$. It shows the differences between the angles at location $y/D<0.008$. At $\pm90^\circ$ there is recirculation at the lower surface of the rough cylinder, with maximum velocity at $\theta=60^\circ$. The maximum velocity for Re>20000 is larger than for Re=10000. Kumarasamy and Barlow report vortex suppression in a stationary cylinder may result from the stability mechanism, as the kinematic conditions at the wall minimally affect the critical gap ratio. In a stationary cylinder a strong correlation between the periodic vortex mechanism and the position of the maximum mean velocity in the gap, is reported by Kim et al. They also note that regular vortex formation takes place in similar regions to those identified in our study. As the maximum velocity is at the lower surface of the cylinder, it suggests the surface roughness has affected the separation process. Therefore, an investigation of separation is essential to understand mechanisms to reduce drag.

Velocity profiles for variations in Reynolds number show at Re>20000 the velocity magnitude after separation is higher than at Re<10000, in each case the maximum value is at the lower surface of the cylinder. A fully-developed recirculation region occurs on the cylinder surface at $90^\circ$. The area of recirculation for Re<10000 is larger than for Re>20000, probably because of more dominant
vertical effects from rotation in lower Re. However, dimensionless velocity \(\left(V/V_{U_0}\right)\) values indicate high velocity for \(Re>20000\) relative to \(Re<10000\), evidencing larger inertial effects.

Figure 7: Velocity profile against \(y/D\) at azimuth angle +30°, +60° and +90° for non-rotating cylinder in range 10000 ≤ Re ≤ 20000 (negative angles are not included due to symmetry) [24]

CONCLUSION

The effect on flow of a rotating circular cylinder with surface roughness has been investigated. Velocity and the intrinsic nature of flow patterns are investigated for a range of Reynolds number and speed of rotation. The lightweight motor configuration facilitates the rotation with minimal vibration or impact on the accuracy of the wind tunnel measurements. From the results of the current study the following conclusions are reached.

1. The flow characteristics show comparable behaviours in the experimental and simulation approaches. A two-dimensional method is very predictive of turbulent flow, due to faster convergence. However, the potential of the method has not been fully investigated, as this study is restricted to velocity magnitude and flow characteristics. More expansive studies, to include drag force, would be beneficial in verifying the applicability of this method.

2. Surface roughness causes a delay in flow separation in the near-wake of a rotating cylinder, which decreases pressure difference across the areas immediately in front and behind the cylinder. From this the conclusion reached is that drag coefficients are lower when there is surface roughness.

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Rotational Effects on Vortex Shedding Behaviour of A Cylinder With Surface Roughness – An Experimental PIV And Computational Approach

34